MATLAB

Programmer’s

Guide for

LCLS physicists

(Version 0.8)

9/22/08

0 REQUIREMENTS...............................................................................................................................4

1 BASICS .................................................................................................................................................5

1.1 SETTING UP THE ENVIRONMENT ....................................................................................................5

1.2 STARTING MATLAB ....................................................................................................................5

1.3 DIRECTORIES.................................................................................................................................5

1.4 CVS ..............................................................................................................................................5

1.4.1 Basic concept ...........................................................................................................................5

1.4.2 CVS Commands .......................................................................................................................6

1.4.2.1 Checkout ...................................................................................................................................... 6

1.4.2.2 Commit ........................................................................................................................................ 6

1.4.2.3 Update .......................................................................................................................................... 6

1.4.2.4 Add .............................................................................................................................................. 6

1.4.2.5 Remove ........................................................................................................................................ 6

1.4.2.6 Diff............................................................................................................................................... 6

1.4.2.7 Other commands .......................................................................................................................... 7

1.4.3 CVSWEB ..................................................................................................................................7

1.4.4 Guidelines ................................................................................................................................7

2 LABCA .................................................................................................................................................8

2.1 GENERAL CONCEPTS .....................................................................................................................8

2.1.1 Parameters and return values..................................................................................................8

2.1.2 Type .........................................................................................................................................8

2.1.3 Timestamp format ....................................................................................................................8

2.1.4 Exceptions................................................................................................................................8

2.1.5 Timeouts ..................................................................................................................................9

2.2 BASIC COMMANDS ........................................................................................................................9

2.2.1 lcaGet ......................................................................................................................................9

2.2.2 lcaPut, lcaPutNoWait ............................................................................................................10

2.3 MONITORS...................................................................................................................................11

2.3.1 lcaSetMonitor ........................................................................................................................12

2.3.2 lcaNewMonitorValue .............................................................................................................12

2.3.3 lcaClear .................................................................................................................................13

2.4 NETWORK-RELATED SETTINGS ....................................................................................................13

2.4.1 Timeout ..................................................................................................................................14

2.4.2 Retry count.............................................................................................................................14

2.4.3 Default configuration.............................................................................................................15

2.5 OTHER.........................................................................................................................................15

3 AIDA ...................................................................................................................................................16

3.1 JAVA SETUP .................................................................................................................................16

3.2 BROWSING NAMES ......................................................................................................................16

3.3 RETRIEVING DATA.......................................................................................................................16

3.4 MISCELLANEOUS.........................................................................................................................18

4 BEAM SYNCHRONOUS ACQUISITION .....................................................................................19

4.1 RESERVING AN EVENT DEFINITION ..............................................................................................19

4.2 CHANGING DEFAULT PARAMETERS .............................................................................................20

4.3 STARTING DATA ACQUISITION .....................................................................................................20

4.4 RELEASING AN EVENT DEFINITION ..............................................................................................21

4.5 AN EXAMPLE SCRIPT ...................................................................................................................21

6 IMAGE MANAGEMENT ................................................................................................................23

6.1 OVERVIEW ..................................................................................................................................23

6.2 GLOBAL DATA .............................................................................................................................23

6.3 GUI APPLICATIONS .....................................................................................................................23

6.3.1 Image acquisition...................................................................................................................23

6.3.2 Image analysis .......................................................................................................................24

6.3.3 Image browser .......................................................................................................................24

6.4 CAMERA INITIALIZATION ............................................................................................................25

6.5 BUFFERED IMAGE ACQUISITION...................................................................................................25

6.6 RAW IMAGE PROCESSING ............................................................................................................26

6.7 OTHER FUNCTIONS ......................................................................................................................26

6.8 DATA STRUCTURES ......................................................................................................................27

6.8.1 Camera ..................................................................................................................................27

6.8.2 Dataset...................................................................................................................................27

6.8.3 ImgAnalysisData ...................................................................................................................28

6.8.4 ImgBrowserData ...................................................................................................................29

6.8.5 ImgManData..........................................................................................................................29

6.8.6 IpOutput.................................................................................................................................30

6.8.7 IpParam .................................................................................................................................30

6.8.8 RawImg ..................................................................................................................................32

7 CMLOG ..............................................................................................................................................34

7.1 STARTING CMLOG BROWSER .......................................................................................................34

7.2 LOGGING MESSAGES ...................................................................................................................34

8 MISCELLANEOUS FUNCTIONS ..................................................................................................35

8.1 LCA2MATLABTIME ......................................................................................................................35

8.2 LCATS2PULSEID..........................................................................................................................35

9 AN EXAMPLE SESSION .................................................................................................................36

APPENDIX A MAD/EPICS/SLC NAMES .......................................................................................38

APPENDIX B EPICS/SLC ATTRIBUTES ......................................................................................43

9.1 MAGNET ATTRIBUTES .................................................................................................................43

APPENDIX C AIDA TYPES..............................................................................................................44

APPENDIX D TEST PVS ...................................................................................................................45

**0 Requirements**

\* A UNIX/AFS account

<http://www2.slac.stanford.edu/comp/slacwide/account/account.html>

\* A Red Hat 4 (or compatible linux) machine to log onto, e.g.

lcls-dev2.slac.stanford.edu

**1 Basics**

**1.1 Setting up the environment**

After you log onto a Linux machine using your AFS account for the first time, you have to add the following line to the file .cshrc in your home directory:

source /afs/slac/g/lcls/tools/script/ENVS.csh

If you need access to OTR images or similar data, also append this line

setenv EPICS\_CA\_MAX\_ARRAY\_BYTES 40000000

If you log from Windows PC, you should also add the line:

setenv DISPLAY = your\_IP\_address:0

where your\_IP\_address can be found after e.g. running ipconfig on Windows. Note: All strings are case-sensitive.

**1.2 Starting MATLAB**

If you want the full development environment, type

matlab

to start the full GUI version

If you want to run applications only and/or do some basic scripting (recommended), type

matlab -nodesktop -nosplash

to start the fully working command-line version that requires much less resources.

**1.3 Directories**

If you want to share your tested scripts, copy them to

/afs/slac/g/lcls/matlab/toolbox

MATLAB scripts from LCLS software engineering team are in

/afs/slac/g/lcls/matlab/script

**1.4 CVS**

You can use CVS to keep track of changes to your scripts, enable collaborative editing, compare to previous versions, etc.

**1.4.1 Basic concept**

CVS keeps up-to-date copies of your files in a single repository, and you along with other people work with copies of these files in a local directory. Think of CVS as a hyper- modern library where you can edit books.

**1.4.2 CVS Commands**

All CVS commands follow the keyword cvs.

1.4.2.1 Checkout

To start working with CVS, you must check out a module (directory).

>> cvs checkout matlab/toolbox

1.4.2.2 Commit

After you made changes to a local file (and tested it), you can commit it back to the repository.

>> cvs commit matlab/toolbox/moments.m

Don’t forget to enter a short, but comprehensive comment!

1.4.2.3 Update

You can update your local directory with files from the repository, if you didn’t change their content yet.

>> cvs update

cvs update: Updating matlab

1.4.2.4 Add

If you created a new local file, you can put it into the CVS repository.

>> cvs add matlab/toolbox/hist2.m

1.4.2.5 Remove

If you removed a local file, you can remove it from the CVS repository.

>> cvs remove matlab/toolbox/hist2.m

1.4.2.6 Diff

Sometimes you want to know how your local files differ from the ones in the repository.

>> cvs diff matlab/toolbox/hist2.m

1.4.2.7 Other commands

See for a comprehensive list of other CVS commands here

<http://www.cvsnt.org/wiki/CvsCommand>

**1.4.3 CVSWEB**

There is a website that gives you graphical access to the CVS repository

[www.slac.stanford.edu/cgi-wrap/cvsweb/matlab/toolbox/?cvsroot=LCLS](http://www.slac.stanford.edu/cgi-wrap/cvsweb/matlab/toolbox/?cvsroot=LCLS)

**1.4.4 Guidelines**

Some good guidelines for using CVS can be found here

<http://dotat.at/writing/cvs-guidelines.html>

**2 LabCA**

Interface to EPICS, the LCLS control system

The labCA toolbox wraps the essential ChannelAccess routines and makes them accessible from the MATLAB programs.

**2.1 General concepts**

**2.1.1 Parameters and return values**

All labCA calls take a PV argument identifying the EPICS process variable the user wants to access. EPICS PVs are plain ASCII strings that follow the pattern

<device>:<attribute>

LabCA is capable of handling multiple PVs in a single call; they are simply passed as a cell-array of strings, e.g.:

pvs = { 'device:xyz'; 'PVa'; 'anotherone' }

**2.1.2 Type**

Unless all PVs are of native ‘string’ type or conversion to ‘string’ is enforced explicitly

(type char), labCA always converts data to double.

Legal values for type are byte, short, long, float, double, native, or char (for strings).

**2.1.3 Timestamp format**

ChannelAccess timestamps provide the number of nanoseconds since 00:00:00 UTC, January 1, 1970. LabCA translates the timestamp into a complex number with the seconds in the real and nanoseconds in the imaginary parts.

To convert timestamps into MATLAB format use epics2matlabTime (see 8.1).

**2.1.4 Exceptions**

If a labCA command cannot execute correctly, it prints an error message and throws an exception. If the exception is not caught, the execution is aborted (look for details in the MATLAB manual).

>> try lcaGet('gibberish') catch

'Reading from PV ''gibberish'' produced this error'

end

multi\_ezca\_get\_nelem - ezcaGetNelem(): could not find process variable

: gibberishError: Errors encountered... ans =

Reading from PV 'gibberish' produced this error

**2.1.5 Timeouts**

Since labCA is used for accessing data via network, your function calls can timeout (see

2.4).

**2.2 Basic commands**

**2.2.1 lcaGet**

[value, timestamp] = lcaGet(pvs, nmax, type)

Description

Read a number of PVs.

Parameters

pvs

m x 1 cell- matrix of m strings.

nmax (optional)

Maximum number of elements (per PV) to retrieve (i.e. limit the number of

columns of value to nmax).

If set to 0 (default), all elements are fetched and the number of columns in the

result matrix is set to the maximum number of elements among the PVs. This parameter is useful to limit the transfer time of large waveforms.

type (optional)

A string specifying the data type to be used for the channel access data transfer.

Returns

value

The m x n result matrix. n is automatically assigned to accommodate the PV with the most elements.

Excess elements of PVs with less than n elements are filled with NaN values. LabCA fills the rows corresponding to INVALID PVs with NaNs. In addition, warning messages are printed to the console if a PV's alarm status exceeds a configurable threshold.

timestamp

m x 1 column vector of complex numbers holding the CA timestamps of the requested PVs.

The timestamps count the number of seconds (real part) and fractional

nanoseconds (imaginary part) elapsed since 00:00:00 UTC, Jan. 1, 1970.

Example

>> [values, timestamps] = lcaGet({'MIKE:BEAM'; 'MIKE:BEAM:RATE'}, 0,

'char')

values =

'ON'

'1'

timestamps =

1.0e+09 \*

1.1546 + 0.8052i

1.1546 + 0.5014i

>> timestamps(1), timestamps(2)

ans =

1.1546e+09 + 8.0522e+08i

ans =

1.1546e+09 + 5.0136e+08i

**2.2.2 lcaPut, lcaPutNoWait**

lcaPut(pvs, value, type)

lcaPutNoWait(pvs, value, type)

Description

Write values to a number of PVs, which may be scalars or arrays of different dimensions.

It is possible to write the same value to a collection of PVs.

lcaPut will wait until the request is processed on the server, lcaPutNoWait returns immediately.

Parameters

pvs

value

m x 1 cell- matrix of m strings.

A matrix or a row array of values to be written to PVs. In latter case, the same value is written to all m PVs.

type (optional)

A string specifying the data type to be used for the channel access data transfer

(see 2.1.2)

Example

>> lcaPut('MIKE:BEAM:RATE', 5)

>> lcaGet('MIKE:BEAM:RATE')

ans =

5

**2.3 Monitors**

Background

There is often a case where you need to wait until a PV value changes. While the code below works

while(1)

initialValue = lcaGet(‘waveformPV’);

currentValue = lcaGet(‘waveformPV’);

if ~isequal(currentValue, initialValue)

%do somet break;

end

unnecessary network traffic can be the result if waveformPV stores big amount of data. To counter, labCA allows you to ask whether a PV value has changed. Then, you get the new value using lcaGet.

end

**2.3.1 lcaSetMonitor**

lcaSetMonitor(pvs, nmax, type)

Description

Set a ”monitor” on a set of PVs. Use the lcaNewMonitorValue to check monitor status (local flag). If new data is available, it is retrieved using the lcaGet call. Use the lcaClear call to remove monitors on a channel.

Parameters

pvs

m x 1 cell- matrix of m strings.

nmax (optional)

Maximum number of elements (per PV) to monitor. If set to 0, all elements are fetched.

type (optional)

A string specifying the data type to be used for the channel access data transfer.

The native type is used by default. The type specified for the subsequent lcaGet

call should match the monitor's data type.

Example

>> lcaSetMonitor(‘MIKE:BEAM’)

**2.3.2 lcaNewMonitorValue**

[flags] = lcaNewMonitorValue(pvs, type)

Description

Check if monitored PVs need to be read, i.e. if fresh data is available (due to initial

connection or changes in value and/or severity status). Reading the actual data must be

done using lcaGet.

Parameters

pvs

m x 1 cell- matrix of m strings.

type (optional)

A string specifying the data type to be used for the channel access data transfer.

The native type is used by default. Note that monitors are specific to a particular data type and therefore lcaNewMonitorValue will only report the status for a monitor that had been established by lcaSetMonitor with a matching type.

Returns

flags

A cell- array of flag values. A value of 0 indicates that no new data is available - the monitored PV has not changed since it was last read. A value of 1 indicates that new data is available for reading (with lcaGet). A negative flag value indicates a problem:

-1: no monitor established (lcaSetMonitor never called for this PV/data type)

-2: non-existing PV (no successful CA search so far),

-3: invalid type argument,

-4: invalid PV argument,

-10: currently no connection.

Example

>> lcaNewMonitorValue({'a';'b'})

ans =

-2

-2

**2.3.3 lcaClear**

lcaClear(pvs)

Description

Disconnect PVs. All monitors on the target channel(s) are cancelled/released as a

consequence of this call.

Parameters

pvs (optional)

m x 1 cell- matrix of m strings. If omitted, disconnects all PVs.

Example

>> lcaClear

**2.4 Network-related settings**

The default labCA timeout for ChannelAccess calls is 0.1s and the default number of retries is 299. This means that if something does not work on the server, the labCA

commands will wait for up to 29.9s before they return. We recommend changing these values.

**2.4.1 Timeout**

currentTimeout = lcaGetTimeout()

Description

Retrieve current timeout (in seconds).

Returns

currentTimeout

Current timeout in seconds

lcaSetTimeout(newTimeout)

Description

Set the new timeout.

Parameters

newTimeout

New timeout in seconds.

Example

>> lcaSetTimeout(0.1)

>> lcaGetTimeout ans =

0.1000

**2.4.2 Retry count**

currentRetryCount = lcaGetRetryCount()

Description

Retrieve the number of retries.

Returns

currentRetryCount

lcaSetRetryCount(newRetryCount)

Description

Set the number of retries.

Parameters

newRetryCount

Example

>> lcaSetRetryCount(10)

>> lcaGetRetryCount ans =

10

**2.4.3 Default configuration**

You may want to choose to include the default LCLS labCA configuration script

lcaInit in your startup.m file. See MATLAB documentation for details.

**2.5 Other**

For all supported labCA commands see

[http://www.slac.stanford.edu/~strauman/labca/manual/node2.html](http://www.slac.stanford.edu/%7Estrauman/labca/manual/node2.html)

**3 AIDA**

Interface to SLC model data

SLC model data (e.g. TWISS parameters) is not accessible via ChannelAccess. Instead, you must use the Java-based library called AIDA (Accelerator Integrated Data Access).

**3.1 Java setup**

Make sure you have a java.opts file in the directory from which you start MATLAB.

**3.2 Browsing names**

You can browse AIDA names by typing

aidalist(device, attribute)

As a temporary solution, this function will prompt for your password.

Parameters

device

AIDA device name

attribute (optional)

AIDA attribute name

Note: As a wild character, you can use the % character (but NOT \*). However, in the device parameter you must at least include one other character (also, be mindful of the output).

Returns

The output is a list of names known to AIDA.

Example

>> aidalist(‘QUAD:IM20:221’, ‘Z%’)

chevtsov@flora’s password:

QUAD:IM20:221 Z QUAD:IM20:221 ZTIM

ans =

0

**3.3 Retrieving data**

To get data, use the function aidaget(aida\_name, type, params) Parameters

aida\_name

AIDA name following the pattern

<device>//<attribute>

type

Note: Device/attribute names used by AIDA differ from the ones used by EPICS, see Appendix A.

(optional) case-insensitive string. Choose type from the table in Appendix C.

params

(optional) a cell array of AIDA parameters. Use the “=” notation for each parameter and value.

Returns

SLC value(s) of the specified type

Example 1

>> aidaget('YCOR:PR12:1052//BACT', ‘double’)

Fri Sep 15 11:58:48 PDT 2006: Making connection to Name Service

Fri Sep 15 11:58:48 PDT 2006: Making connection to daServer ans =

0

Example 2

>> r = aidaget('BPMS:IA20:221//R', 'doublea', {'B=BPMS:IA20:511'}); Fri Sep 15 12:00:06 PDT 2006: Making connection to Name Service

Fri Sep 15 12:00:06 PDT 2006: Making connection to daServer

>> rMatrix = reshape(r, 6, 6)' rMatrix =

Columns 1 through 3

[ -0.7087] [ 0.1886] [-7.0392e-19] [ 0.1703] [ -0.1078] [ 1.6913e-19] [ 4.6419e-19] [-9.7456e-20] [ -0.4677] [ 1.5362e-19] [ 6.2426e-20] [ -0.1548] [-2.5244e-29] [-3.9345e-30] [ 0]

[ 0] [ 0] [ 0] Columns 4 through 6

[ 1.8859e-19] [0] [-2.4379e-32] [-1.0779e-19] [0] [ 1.0095e-32] [ 0.0975] [0] [ 0] [ -0.0624] [0] [ 0] [ 0] [1] [-3.2001e-28] [ 0] [0] [ 0.0443]

**3.4 Miscellaneous**

For more information like possible parameters, please see

<http://www.slac.stanford.edu/grp/cd/soft/aida>

**4 Beam synchronous acquisition**

An LCLS event system has been setup to read devices synchronous with beam crossing, such as BPMS and toroids. This system can be used from within Matlab with a few simple calls. Note that this is not implemented for image data collection. See separate section on collecting image data and collecting image data along with other beam synchronous devices. Figure 4.1 shows how the IOC looks at the EVR signal and BPM data to fill its BSA buffers.

Timing pattern from EVG

EVR

IOC

EDEF

e.g. 10 Hz

BSA Buffers

For 20 EDEFs

BPMS:IN20:221:XHSTTH BPMS:IN20:221:YHSTTH BPMS:IN20:221:TMITHSTTH

From

BPM

BPM

module

Data at full rate

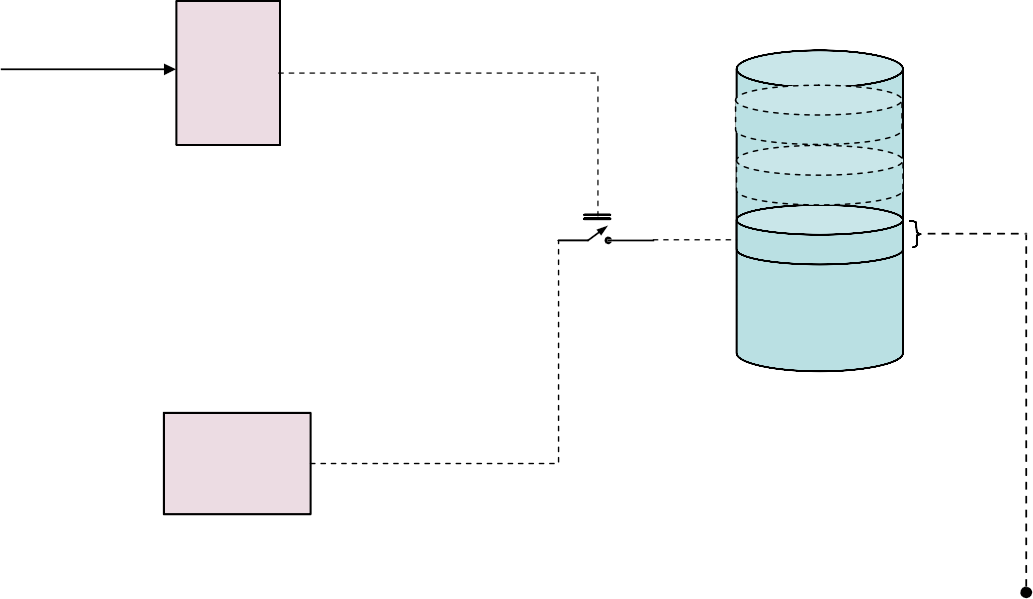
Controls network

OPI

Matlab

X=lcaGet(‘BPMS:IN20:221:XHSTTH’);

Figure 1: Conceptual data flow for Beam Synchronous Acquisition



**4.1 Reserving an event definition**

eDefNumber = eDefReserve(myName)

Description

Reserves an event definition for your use.

Parameters

myName

a unique name for your application

Returns

ID of an event definition

**4.2 Changing default parameters**

eDefParams (eDefNumber, navg, nrpos, incmSet, incmReset, excmSet, excmReset )

Description

Changes defaults of the supplied arguments

Parameters

eDefNumber

ID of an event definition

navg

nrpos

Number of pulses to average per reading To reduce the amount of jitter, you may choose to average several pulses together to get an averaged value. Default is no averaging; maximum is currently 10.

Number of readings to take, which is the buffer size you wish to acquire. Default is one reading; maximum is currently 2800.

incmSet, incmReset, excmSet, excmReset

Optional Inclusion and Exclusion Timing Modifiers. Specific PNET bits you wish to be present or absent during your acquisition, such as ONE\_HERTZ.

See the PNBN database for a list of available PNET bits by viewing the PVs MP00:PNBN:[1..150]:NAME. Defaults to the values in VX00:DGRP:1150:INCM and VX00:DGRP:1150:EXCM.

**4.3 Starting data acquisition**

elapsedTime = eDefAcq (eDefNumber, timeout)

Description

Starts the data acquisition cycle. If the elapsed time is less than the timeout specified

then your buffers are completely populated with the number of readings you specified, otherwise your buffers are populated with the number of readings the system was able to collect in the time allotted for data acquisition. This function blocks Matlab execution.

Please see the script for a non-blocking example.

You collect your data from PVs with lcaGet. If, for example, you're interested in the device BPMS:IN20:221, your data can be found in the following PVs:

BPMS:IN20:221:XHST[eDefNumber]

Waveform containing all BPMS X values collected

BPMS:IN20:22:1:X[eDefNumber]

The last BPMS X value collected, handy when you only requested one reading

BPMS:IN20:221:X[eDefNumber].H

Rms of the last BPMS X value collected

BPMS:IN20:221:MEASCNT[eDefNumber]

Number of beam pulses used in your acquisition

Data for all devices known to the event definition system is available. There is no need to specify a device list for data acquisition. For en explanation of all available devices, please see the documentation on event definitions. For a complete list of BSA pvs, please try the Aida query LCLS//\* at https://seal.slac.stanford.edu/aidaweb

**4.4 Releasing an event definition**

eDefRelease (eDefNumber)

Description

Releases your event definition for use by another control system application. Note that

you can perform many data acquisition and collection cycles before releasing your event definition reservation.

Parameters

eDefNumber

ID of an event definition

**4.5 An example script**

The example can be found in eDefExample.m

% Choose unique name myName = 'Matlab eDef'; myNAVG = 1;

myNRPOS = 20;

timeout = 3.0; % seconds

% Reserve an eDef number

myeDefNumber = eDefReserve(myName);

% Make sure I got an eDef Number

if isequal (myeDefNumber, 0)

disp ('Sorry, failed to get eDef');

else

disp (sprintf('%s I am eDef number %d',datestr(now),myeDefNumber));

% set my number of pulses to average, etc... Optional, defaults to no

% averaging with one pulse and DGRP INCM & EXCM.

eDefParams (myeDefNumber, myNAVG, myNRPOS, {'TS4'},{''},{'TS1'},{''});

acqTime = eDefAcq(myeDefNumber, timeout);

if (acqTime < timeout)

disp (sprintf ('%s Data collection complete, took %.1f seconds', datestr(now), acqTime));

else

disp (sprintf ('%s Data collection timed out. Data available for

%.1f seconds', datestr(now), acqTime));

end

% read data, note that data stays until you give up your eDef

xVec = lcaGet(sprintf('BPMS:IN20:221:XHST%d',myeDefNumber)); yVec = lcaGet(sprintf('BPMS:IN20:221:YHST%d',myeDefNumber)); iVec = lcaGet(sprintf('BPMS:IN20:221:TMITHST%d',myeDefNumber));

pidVec = lcaGet(sprintf('PATT:SYS0:1:PULSEIDHST%d',myeDefNumber));

disp(sprintf(‘Event definition (EVG) claimed to have collected %d steps’, eDefCount(myeDefNumber));

% Give up eDef

eDefRelease(myeDefNumber);

**6 Image management**

The image management (ImgMan) toolbox is a set of Matlab functions and GUIs for online and off-line processing of grayscale radiation images resulting from impact of electrons on a screen in the beam line. The toolbox includes applications for acquiring, browsing, and analyzing images.

**6.1 Overview**

ADD PICTURE!!! (Coming April 12th)

**6.2 Global data**

ImgMan accesses raw image data and makes available processed images and beam data through a global variable called gIMG\_MAN\_DATA, which is an instance of the ImgManData struct (see 6.8.5).

**6.3 GUI applications**

**6.3.1 Image acquisition**

h = imgAcq\_main(cameraArray)

Description

Starts the image acquisition application.

Parameters

cameraArray

A row cell array of camera structs (see 6.8.1).

Returns

The handle of the main image acquisition figure.

Example

imgAcq\_main();

**6.3.2 Image analysis**

h = imgAnalysis\_main(imgAnalysisData, left, top)

Description

Starts the image analysis application.

Parameters

imgAnalysisData (optional)

An instance of the imgAnalysisData struct (see 6.8.3).

left (optional)

top (optional)

X coordinate of the upper left corner of the figure.

Y coordinate of the upper left corner of the figure.

Returns

The handle of the main image analysis figure.

Example

h = imgAnalysis\_main();

set(h, ‘name’, ‘My Image Analysis’);

**6.3.3 Image browser**

h = imgBrowser\_main(imgBrowserData, left, top)

Description

Starts the image browser application. Note: image browser displays valid datasets only.

Parameters

imgBrowserData (optional)

An instance of the imgBrowserData struct (see 6.8.4).

left (optional)

top (optional)

X coordinate of the upper left corner of the figure.

Y coordinate of the upper left corner of the figure.

Returns

The handle of the main image browser figure.

Example

h = imgBrowser\_main();

set(h, ‘name’, ‘My Browser’);

**6.4 Camera initialization**

cameraArray = imgAcq\_initCameraProperties()

Description

Initializes the properties of all available cameras. This function is designed to be edited as

if it was a properties file.

Returns

A row cell array of camera structs (see 6.8.1).

Example

TO DO

**6.5 Buffered image acquisition**

rawImgArray = imgAcq\_runBufferedAcq(camera, nrBgImgs, nrBeamImgs, saveBufferedImgs, progHandles)

Description

Executes the buffered image acquisition and returns a list of images, sorted by

timestamps. Background images are retrieved before beam images. If you request 0

background images, a saved background image will be retrieved first.

Parameters

camera

An instance of the camera struct (see 6.8.1).

nrBgImgs

Number of background images (>=0).

nrBeamImgs

Number of beam images (>=0).

saveBufferedImgs (optional)

A flag indicating whether buffered images should be saved locally. Default value is 1.

progHandles (optional)

Handles of the GUI that contains a progress panel. Default value is [].

Returns

A row cell array of rawImg structs (see 6.8.8).

Example

TODO

**6.6 Raw image processing**

ipOutput = imgProcessing\_processRawImg(rawImg, camera, ipParam, bgImg)

Description

Processes raw image data from the specified camera according to the specified image

processing parameters.

Parameters

rawImg

An instance of the rawImg struct (see 5.8.8).

camera

ipParam

An instance of the camera struct (see 5.8.1). An instance of ipParam struct (see 5.8.7).

bgImg (optional)

A grayscale image that represents the background noise.

Returns

An instance of the ipOutput struct (see 5.8.6).

Example

TO DO

**6.7 Other functions**

|  |  |
| --- | --- |
| Name | Description |
| imgAcq\_epics\* | A set of functions for low(er)-level  interactions with EPICS. |

imgData\_construct\* A set of functions for creating default

**6.8 Data structures**

**6.8.1 Camera**

Default constructor: imgData\_construct\_camera

|  |  |  |  |
| --- | --- | --- | --- |
| Field | Description | Default value | Type |
| bufferSize | Size of the buffer for  images this camera can  take. | 0 | Integer |
| hasScreen | Flag indicating whether  this camera points at a  screen. | 0 | Boolean. |
| isProd | A flag indicating  whether this camera is  on production network. | 1 | Boolean. |
| label | The label of the screen. | ‘N/A’ | String. |
| maxNrBeamImgs | Due to high costs of the  screens, we decided to limit the number of beam images that users  can request per  measurement. | 0 | Integer. |
| pvPrefix | Prefix for PVs that  deliver other camera  parameters. | ‘N/A’ | String. |
| updatePause | Time between requests  for live images from  this camera. | 0 | Double (>= 0). |

**6.8.2 Dataset**

Default constructor: imgData\_construct\_dataset

|  |  |  |  |
| --- | --- | --- | --- |
| Field | Description | Default value | Type |
| camera | The camera which  datasets was taken from. | See 5.8.1. | Camera struct. |
| ipOutput | A list of image  processing output parameters for  external applications. Note: ImgMan does not  read it. | [] (empty) | Row cell array of  ipOuput structs (see  5.8.6). |

|  |  |  |  |
| --- | --- | --- | --- |
| ipParam | A set of image  processing parameters for  external applications. Note: ImgMan does not  read this field. | [] (empty) | IpParam struct (see  5.8.7). |
| isValid | A flag indicating the  validity of the dataset. ImgBrowser  does not show  invalid datasets. | 1 | Boolean. |
| label | The label of this  dataset. | ‘n/a’ | String. |
| masterCropArea | The area of the master crop region. | [] | Four-element row  array of doubles, [xmin ymin width  height] each in  default spatial coordinates. |
| nrBgImgs | Number of  background images in the dataset. ImgMan treats the  first nrBgImgs images in the dataset as  background images. | 0 | Integer. |
| nrBeamImgs | Number of beam  images in the  dataset. | 0 | Integer. |
| rawImg | A list of raw image parameters. | [] (empty) | Row cell array of  rawImg structs (see  5.8.8). |

**6.8.3 ImgAnalysisData**

Default constructor: imgData\_construct\_imgAnalysis

|  |  |  |  |
| --- | --- | --- | --- |
| Field | Description | Default value | Type |
| dsIndex | The index of a  dataset (which doesn’t have to be  valid). | 1 | Integer. |
| imgIndex | The index of an  image in the  selected dataset. | 1 | Integer. |

|  |  |  |  |
| --- | --- | --- | --- |
| ipOutput | A set of image  processing output parameters. | [] (empty) | IpOutput struct (see  5.8.6). |
| ipParam | A set of image  processing parameters. | Default structure. | IpParam struct (see  5.8.7) |

**6.8.4 ImgBrowserData**

Default constructor: imgData\_construct\_imgBrowser

|  |  |  |  |
| --- | --- | --- | --- |
| Field | Description | Default value | Type |
| fitPlane | The plane of the  initial fits. | ‘x’ | ‘x’ or ‘y’ |
| imgOffset | The offset of the  displayed images. | 0 | Integer. |
| ipOutput | Initial set of image  processing output  parameters. | [] (empty) | IpOutput struct (see  5.8.6). |
| ipParam | Initial set of image  processing parameters. | [] (empty) | IpParam struct (see  5.8.7). |
| nrDsTabs | The number of  visible dataset tabs in the ImgBrowser  figure. You should adjust it if you have datasets with long  labels. | 5 | Integer. |
| validDsIndex | The index of the  selected valid dataset. ImgMan  uses its own defaults, if you provide a negative  value. | -1 | Integer. |
| validDsOffset | The offset of the  displayed datasets. ImgMan uses its  own defaults, if you provide a negative value. | -1 | Integer. |

**6.8.5 ImgManData**

Default constructor: imgData\_construct\_imgMan

|  |  |  |  |
| --- | --- | --- | --- |
| Field | Description | Default value | Type |
| dataset | A list of raw image datasets. | [] (empty) | Row cell array of  dataset structs (see  5.8.2). |
| ipOutputChanged | A flag indicating  whether new processed images  and/or beam data is  available. Note: ImgMan sets this  field only to 1; it is  up to the client to reset it to 0. | 0 | Boolean. |
| isDirty | A flag indicating  whether the datasets  need to be saved. | 0 | Boolean. |

**6.8.6 IpOutput**

Default constructor: imgData\_construct\_ipOutput

|  |  |  |  |
| --- | --- | --- | --- |
| Field | Description | Default value | Type |
| beamlist | A set of beam fit  parameters. | [] (empty) | TO DO |
| isValid | The flag indicating  whether the raw image is valid according to the  image processing algorithm. | [] | Boolean. |
| offset  .x  .y | Pixel coordinates of the  upper left corner of the  processed image (useful e.g. if the raw image  was cropped). | 0 and 0 | Double. |
| procImg | The result of image  processing. | 0 | A matrix of  doubles. |

**6.8.7 IpParam**

Default constructor: imgData\_construct\_ipParam

|  |  |  |  |
| --- | --- | --- | --- |
| Field | Description | Default value | Type |

|  |  |  |  |
| --- | --- | --- | --- |
| algIndex | ImgMan’s image  processing routine returns sets of beam  data for each of the pre-defined algorithms in bulk.  This field is used to  display data that resulted from an algorithm with the  particular index. | 1 | Integer. |
| annotation  .centroid  .current.color | Color of the current beam centroid mark. | [0 0 0] (black) | RGB color. |
| annotation  .centroid  .current.flag | Flag indicating  whether to display the current beam  centroid mark. | 0 | Boolean. |
| annotation  .centroid  .goldenOrbit.color | Color of the golden  orbit beam centroid mark. | [1 0.84 0] (gold) | RGB color. |
| annotation  .centroid  .goldenOrbit.flag | Flag indicating  whether to display the golden orbit  beam centroid mark. | 0 | Boolean. |
| annotation  .centroid  .laserBeam.color | Color of the laser beam centroid mark. | [1 0 0] (red) | RGB color. |
| annotation  .centroid  .laserBeam.flag | Flag indicating  whether to display the laser beam  centorid mark. | 0 | Boolean. |
| beamSizeScaleUnit | The scale unit of the  beam size. | ‘pix’ | ‘pix’, or ‘mm’ |
| colormapFcn | Name of the  function that creates a colormap. | ‘jet’ | String |
| crop  .auto  .custom | Flags indicating  whether an automatic crop by  the image  processing algorithms or a custom crop is  desired. The flags  should not be set to  1 at the same time. | Auto = 0  Custom = 0 | Boolean. |

|  |  |  |  |
| --- | --- | --- | --- |
| Filter  .floor  .median | Flags indicating  whether a filter should be applied to  the raw image. | Floor = 0  Median = 0 | Boolean. |
| lineWidthFactor | A factor for the  width of the annotation lines (in  proportion to the size of the corresponding  axes). | 1/150 | Double. |
| slice  .index  .plane  .total | The current index,  plane, and total number of slices of  the raw image. ImgMan extracts beam data from the  specified slice only. | Index = 1  Plane = ‘x’ Total = 1 | Index: Integer. Plane: ‘x’ or ‘y’. Total: Integer. |
| nrColors  .max  .min  .val | Maximum,  minimum, and the current number of  colors in the  colormap. | Max = 4084; Min = 64; Val = 256; | Integer. |
| subtractBg  .acquired  .calculated | Flags indicating  whether to subtract  the background noise that is calculated by the  image processing  algorithms, or the average of the background images  in the dataset from  raw images. If both flags are set to 0, no  image processing is  done. The flags should not be set to  1 at the same time. | Acquired = 0  Calculated = 0 | Boolean. |

**6.8.8 RawImg**

Default constructor: imgData\_construct\_rawImg

|  |  |  |  |
| --- | --- | --- | --- |
| Field | Description | Default value | Type |
|  |  |  |  |

|  |  |  |  |
| --- | --- | --- | --- |
| customCropArea | Coordinates of a custom region of interest for the raw image. | [] (empty) | Four-element row  array of doubles, [xmin ymin width  height] each in default spatial coordinates. |
| data | Grayscale image  data that ImgMan retrieves from an IOC. | 0 | Matrix of integers. |
| ignore | A flag for ignoring  the raw image, overriding the  validity field of an  instance of  IpOutput (see  6.8.6). | [] | Boolean or []. |
| timestamp | The time of when  the camera delivered  the raw image to the  IOC. | -1 | LabCA timestamp. |

**7 Cmlog**

LCLS logging facility

All commands can be executed outside MATLAB. Use –help option to get more information about each command.

**7.1 Starting cmlog browser**

To start cmlog from MATLAB, type

unix(‘cmlog –c –u &’)

Note: Don’t forget & or your MATLAB will block!

**7.2 Logging messages**

To log a message to cmlog, type

unix(‘cmlogMsgLine ''some message''’)

**8 Miscellaneous functions**

This chapter describes useful MATLAB functions developed at LCLS.

**8.1 lca2matlabTime**

lca2matlabTime(lcaTS)

Converts labCA timestamp into MATLAB time (number of days since 1/1 0000).

Parameter

lcaTS

LabCA timestamp as acquired through lcaGet.

Example

>> [value, lcaTS] = lcaGet('MIKE:BEAM');

>> matlabTS = lca2matlabTime(lcaTS);

>> datestr(matlabTS, 'mmm dd HH:MM:SS.FFF')

ans =

Aug 23 18:04:18.658

**8.2 lcaTs2PulseId**

lcaTs2PulseId(lcaTS)

Extracts pulse ID from labCA timestamp

Parameter

lcaTS

LabCA timestamp as acquired through lcaGet.

Example

>> [value, lcaTS] = lcaGet('MIKE:BEAM');

>> lcaTs2PulseId(lcaTS);

ans =

16753

**9 An example session**

Log onto a Linux computer

dhcpvisitor21831:~ chevtsov$ ssh noric05

Start MATLAB

chevtsov@noric05 $ matlab -nodesktop –nosplash

Get the status of the (fake) OTR 2 screen

>> lcaGet('MIKE:OTR2:POS')

ans =

'OUT'

Put OTR2 screen in

>> lcaPut('MIKE:OTR2:POS:REQ', 'IN')

Get image from OTR2

>> epicsImg = lcaGet('MIKE:OTR2:IMAGE');

Reshape into a 2D image

>> img = reshape(img, 240, 320);

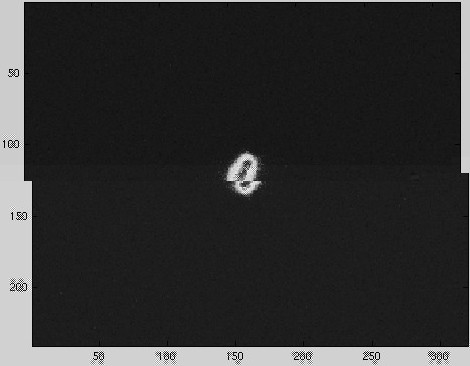
Display image

>> image (img)

Result



*.. : Ls.?:L&..:, Lu..:'"g "d& ':Mi:.*



**Appendix A MAD/EPICS/SLC**

**names**

|  |  |  |
| --- | --- | --- |
| MAD  AM01 | EPICS  MIRR:IN20:191 | SLC  - |
| BL11 | BLEN:LI21:265 | ARRY:LD21:265 |
| BL12 | BLEN:LI21:280 | ARRY:LD21:265 |
| BPM10 | BPMS:IN20:581 | BPMS:IB20:581 |
| BPM11 | BPMS:IN20:631 | BPMS:IB20:631 |
| BPM12 | BPMS:IN20:651 | BPMS:IB20:651 |
| BPM13 | BPMS:IN20:731 | BPMS:IB20:731 |
| BPM14 | BPMS:IN20:771 | BPMS:IB20:771 |
| BPM15 | BPMS:IN20:781 | BPMS:IB20:781 |
| BPM2 | BPMS:IN20:221 | BPMS:IA20:221 |
| BPM21201 | BPMS:LI21:201 | BPMS:LA21:201 |
| BPM21301 | BPMS:LI21:301 | BPMS:LA21:301 |
| BPM21401 | BPMS:LI21:401 | BPMS:LB21:401 |
| BPM21501 | BPMS:LI21:501 | BPMS:LB21:501 |
| BPM3 | BPMS:IN20:235 | BPMS:IA20:235 |
| BPM5 | BPMS:IN20:371 | BPMS:IA20:371 |
| BPM6 | BPMS:IN20:425 | BPMS:IA20:425 |
| BPM8 | BPMS:IN20:511 | BPMS:IA20:511 |
| BPM9 | BPMS:IN20:525 | BPMS:IB20:525 |
| BPMA11 | BPMS:LI21:131 | BPMS:LA21:131 |
| BPMA12 | BPMS:LI21:161 | BPMS:LA21:161 |
| BPMG1 | BPMS:IN20:821 | BPMS:IA20:821 |
| BPMM12 | BPMS:LI21:278 | BPMS:LA21:278 |
| BPMM14 | BPMS:LI21:315 | BPMS:LA21:315 |
| BPMS1 | BPMS:IN20:925 | BPMS:IB20:925 |
| BPMS11 | BPMS:LI21:233 | BPMS:LA21:233 |
| BPMS2 | BPMS:IN20:945 | BPMS:IB20:945 |
| BPMS3 | BPMS:IN20:981 | BPMS:IB20:981 |
| BX01 | BTRM:IN20:661 | BTRM:IM20:661 |
| BX02 | BEND:IN20:751 | BEND:IM20:751 |
| BX11 | BEND:LI21:215 | BEND:LM21:215 |
| BX12 | BEND:LI21:231 | BEND:LM21:231 |
| BX13 | BTRM:LI21:241 | BTRM:LM21:241 |
| BX14 | BTRM:LI21:261 | BTRM:LM21:261 |
| BXG | BTRM:IN20:231 | BTRM:IM20:231 |
| BXH1 | BTRM:IN20:451 | BTRM:IM20:451 |
| BXH2 | BEND:IN20:461 | BEND:IM20:461 |
| BXH3 | BTRM:IN20:475 | BTRM:IM20:475 |
| BXH4 | BTRM:IN20:481 | BTRM:IM20:481 |
| BXS | BEND:IN20:931 | BEND:IM20:931 |
| C21503 | YCOR:LI21:503 | YCOR:LM21:503 |
| CATHODE | CATH:IN20:111 | - |

CE11 COLL:LI21:235 COLL:LA21:235

CQ01 QUAD:IN20:121 QUAD:IM20:121

CQ11 QUAD:LI21:221 QUAD:LM21:221

CQ12 QUAD:LI21:251 QUAD:LM21:251

CR01 CRAD:IN20:237 - CRG1 CRAD:IN20:842 - FC01 FARC:IN20:212 - FCG1 FARC:IN20:898 - FCS1 FARC:IN20:998 - GSDMP DUMP:IN20:899 - HTRUND HTR:IN20:467 -

IM01 TORO:IN20:215 TORO:ID20:215

IM02 TORO:IN20:431 TORO:ID20:431

IM03 TORO:IN20:791 TORO:ID20:791

IMBC1I TORO:LI21:205 TORO:ID20:205

IMBC1O TORO:LI21:277 TORO:ID20:277

IMS1 TORO:IN20:971 TORO:ID20:971

K21\_1B KLYS\_LLRF:LI21:BL101 - K21\_1C KLYS\_LLRF:LI21:BL101 - K21\_1D KLYS\_LLRF:LI21:BL101 - K21\_3B - KLYS:LI21:31

K21\_3C - KLYS:LI21:31

K21\_3D - KLYS:LI21:31

K21\_4A - KLYS:LI21:41

K21\_4B - KLYS:LI21:41

K21\_4C - KLYS:LI21:41

K21\_4D - KLYS:LI21:41

K21\_5A - KLYS:LI21:51

K21\_5B - KLYS:LI21:51

K21\_5C - KLYS:LI21:51

L0A\_ KLYS\_LLRF:IN20:BL701 - L0B\_ KLYS\_LLRF:IN20:BL801 -

L1X

KLYS\_LLRF:LI21:BL201 -

OTR1 OTRS:IN20:541 PROF:IB20:541

OTR11 OTRS:LI21:237 PROF:LA21:237

OTR12 OTRS:LI21:291 PROF:LA21:291

OTR2 OTRS:IN20:571 PROF:IB20:571

OTR3 OTRS:IN20:621 PROF:IB20:621

OTR4 OTRS:IN20:711 PROF:IB20:711

OTRH1 OTRS:IN20:465 PROF:IA20:465

OTRH2 OTRS:IN20:471 PROF:IA20:471

OTRS1 OTRS:IN20:991 PROF:IB20:991

PH01 KLYS\_PMON:IN20:BL365 - PH02 - -

Q21201 - QUAD:LI21:201

Q21301 - QUAD:LI21:301

Q21401 - QUAD:LI21:401

Q21501 - QUAD:LI21:501

|  |  |  |
| --- | --- | --- |
| QA01 | QUAD:IN20:361 | QUAD:IM20:361 |
| QA02 | QUAD:IN20:371 | QUAD:IM20:371 |
| QA11 | QUAD:LI21:131 | QUAD:LM21:131 |
| QA12 | QUAD:LI21:161 | QUAD:LM21:161 |
| QB | QUAD:IN20:731 | QUAD:IM20:731 |
| QE01 | QUAD:IN20:425 | QUAD:IM20:425 |
| QE02 | QUAD:IN20:441 | QUAD:IM20:441 |
| QE03 | QUAD:IN20:511 | QUAD:IM20:511 |
| QE04 | QUAD:IN20:525 | QUAD:IM20:525 |
| QG01 | QUAD:IN20:221 | QUAD:IM20:221 |
| QG02 | QUAD:IN20:811 | QUAD:IM20:811 |
| QG03 | QUAD:IN20:831 | QUAD:IM20:831 |
| QM01 | QUAD:IN20:BL631 | QUAD:IM20:631 |
| QM02 | QUAD:IN20:651 | QUAD:IM20:651 |
| QM03 | QUAD:IN20:771 | QUAD:IM20:771 |
| QM04 | QUAD:IN20:781 | QUAD:IM20:781 |
| QM11 | QUAD:LI21:211 | QUAD:LM21:211 |
| QM12 | QUAD:LI21:271 | QUAD:LM21:271 |
| QM13 | QUAD:LI21:278 | QUAD:LM21:278 |
| QM14 | QUAD:LI21:315 | QUAD:LM21:315 |
| QM15 | QUAD:LI21:335 | QUAD:LM21:335 |
| QS01 | QUAD:IN20:941 | QUAD:IM20:941 |
| QS02 | QUAD:IN20:961 | QUAD:IM20:961 |
| RST1 | STPR:IN20:BL551 | - |
| SDMP | DUMP:IN20:999 | - |
| SOL1 | SOLN:IN20:121 | SOLN:IM20:121 |
| SOL1BK | SOLN:IN20:111 | SOLN:IM20:111 |
| SOL2 | SOLN:IN20:311 | SOLN:IM20:311 |
| SQ01 | QUAD:IN20:122 | QUAD:IM20:122 |
| TCAV0 | KLYS\_LLRF:IN20:BL501 | - |
| TD11 | DUMP:LI21:305 | - |
| VV01 | VVPG:IN20:BL155 | - |
| VV02 | VVPG:IN20:BL435 | - |
| VV03 | VVPG:IN20:BL545 | - |
| VV04 | VVPG:IN20:BL635 | - |
| VVS1 | VVPG:IN20:IS915 | - |
| VVX1 | VVMG:LI21:BL175 | - |
| VVX2 | VMG:LI21:BL195 | - |
| WS01 | WIRE:IN20:BL531 | WIRE:IB20:531 |
| WS02 | WIRE:IN20:BL561 | WIRE:IB20:561 |
| WS03 | WIRE:IN20:BL611 | WIRE:IB20:611 |
| WS04 | WIRE:IN20:BL741 | WIRE:IB20:741 |
| WS11 | WIRE:LI21:BL285 | WIRE:LA21:285 |
| WS12 | WIRE:LI21:BL293 | WIRE:LA21:293 |
| WS13 | WIRE:LI21:BL301 | WIRE:LA21:301 |
| XC00 | XCOR:IN20:121 | XCOR:IM20:121 |
| XC01 | XCOR:IN20:221 | XCOR:IM20:221 |
| XC02 | XCOR:IN20:311 | XCOR:IM20:311 |

|  |  |  |
| --- | --- | --- |
| XC03 | XCOR:IN20:341 | XCOR:IM20:341 |
| XC04 | XCOR:IN20:381 | XCOR:IM20:381 |
| XC05 | XCOR:IN20:411 | XCOR:IM20:411 |
| XC06 | XCOR:IN20:491 | XCOR:IM20:491 |
| XC07 | XCOR:IN20:521 | XCOR:IM20:521 |
| XC08 | XCOR:IN20:641 | XCOR:IM20:641 |
| XC09 | XCOR:IN20:721 | XCOR:IM20:721 |
| XC10 | XCOR:IN20:761 | XCOR:IM20:761 |
| XC11 | XCOR:LI21:101 | XCOR:LM21:101 |
| XC21202 | - | XCOR:LI21:202 |
| XC21302 | - | XCOR:LI21:302 |
| XC21402 | XCOR:LI21:402 | XCOR:LM21:402 |
| XC21502 | - | XCOR:LI21:502 |
| XCA11 | XCOR:LI21:135 | XCOR:LM21:135 |
| XCA12 | XCOR:LI21:165 | XCOR:LM21:165 |
| XCG1 | XCOR:IN20:811 | XCOR:IM20:811 |
| XCG2 | XCOR:IN20:831 | XCOR:IM20:831 |
| XCM11 | XCOR:LI21:191 | XCOR:LM21:191 |
| XCM13 | XCOR:LI21:275 | XCOR:LM21:275 |
| XCM14 | XCOR:LI21:325 | XCOR:LM21:325 |
| XCS1 | XCOR:IN20:911 | XCOR:IM20:911 |
| XCS2 | XCOR:IN20:951 | XCOR:IM20:951 |
| YAG01 | YAGS:IN20:211 | PROF:IA20:211 |
| YAG02 | YAGS:IN20:241 | PROF:IA20:241 |
| YAG03 | YAGS:IN20:351 | PROF:IA20:351 |
| YAG04 | YAGS:IN20:471 | PROF:IA20:471 |
| YAGG1 | YAGS:IN20:841 | PROF:IA20:841 |
| YAGS1 | YAGS:IN20:921 | PROF:IB20:921 |
| YAGS2 | YAGS:IN20:995 | PROF:IB20:995 |
| YC00 | YCOR:IN20:122 | YCOR:IM20:122 |
| YC01 | YCOR:IN20:222 | YCOR:IM20:222 |
| YC02 | YCOR:IN20:312 | YCOR:IM20:312 |
| YC03 | YCOR:IN20:342 | YCOR:IM20:342 |
| YC04 | YCOR:IN20:382 | YCOR:IM20:382 |
| YC05 | YCOR:IN20:412 | YCOR:IM20:412 |
| YC06 | YCOR:IN20:492 | YCOR:IM20:492 |
| YC07 | YCOR:IN20:522 | YCOR:IM20:522 |
| YC08 | YCOR:IN20:642 | YCOR:IM20:642 |
| YC09 | YCOR:IN20:722 | YCOR:IM20:722 |
| YC10 | YCOR:IN20:762 | YCOR:IM20:762 |
| YC11 | YCOR:LI21:102 | YCOR:LM21:102 |
| YC21203 | - | YCOR:LI21:203 |
| YC21303 | - | YCOR:LI21:303 |
| YC21403 | - | YCOR:LI21:403 |
| YCA11 | YCOR:LI21:136 | YCOR:LM21:136 |
| YCA12 | YCOR:LI21:166 | YCOR:LM21:166 |
| YCG1 | YCOR:IN20:812 | YCOR:IM20:812 |
| YCG2 | YCOR:IN20:832 | YCOR:IM20:832 |

|  |  |  |
| --- | --- | --- |
| YCM11 | YCOR:LI21:192 | YCOR:LM21:192 |
| YCM12 | YCOR:LI21:276 | YCOR:LM21:276 |
| YCM15 | YCOR:LI21:325 | YCOR:LM21:325 |
| YCS1 | YCOR:IN20:912 | YCOR:IM20:912 |
| YCS2 | YCOR:IN20:952 | YCOR:IM20:952 |
| - | LGPS:IN20:1 | LGPS:IM20:1 |
| - | LGPS:IN20:2 | LGPS:IM20:2 |
| - | LION:IN20:BL650 | - |
| - | LION:IN20:BL651 | - |
| - | LION:LI21:BL162 | - |
| - | LION:LI21:BL163 | - |
| - | PICS:IN20:BL665 | - |
| - | PICS:IN20:BL755 | - |
| - | PICS:IN20:IS933 | - |
| - | PICS:LI21:BL185 | - |
| - | PICS:LI21:BL232 | - |
| - | PICS:LI21:BL245 | - |
| - | PLIC:IN20:BL221 | - |
| - | PLIC:IN20:BL551 | - |
| - | VGCC:IN20:BL113 | - |
| - | VGCC:IN20:BL221 | - |
| - | VGCC:IN20:BL469 | - |
| - | VGCC:IN20:BL605 | - |
| - | VGCC:IN20:BL775 | - |
| - | VGCC:IN20:BL935 | - |
| - | VGCP:IN20:BL111 | - |
| - | VGHF:IN20:BL111 | - |
| - | VGPR:IN20:BL113 | - |
| - | VGPR:IN20:BL221 | - |
| - | VGPR:IN20:BL469 | - |
| - | VGPR:IN20:BL605 | - |
| - | VGPR:IN20:BL775 | - |
| - | VGPR:IN20:BL935 | - |
| - | VPIO:IN20:BL111 | - |
| - | VPIO:IN20:BL113 | - |
| - | VPIO:IN20:BL235 | - |
| - | VPIO:IN20:BL301 | - |
| - | VPIO:IN20:BL303 | - |
| - | VPIO:IN20:BL375 | - |
| - | VPIO:IN20:BL377 | - |
| - | VPIO:IN20:BL465 | - |
| - | VPIO:IN20:BL605 | - |
| - | VPIO:IN20:BL705 | - |
| - | VPIO:IN20:BL965 | - |
| - | VPIO:IN20:GS811 | - |

**Appendix B EPICS/SLC attributes**

**9.1 Magnet attributes**

(Note: some might not be available yet)

EPICS SLC Description

BACT BACT Physical Units val converted from IACT BACT.ADEL TOLS3 Alarm Delta

BCTRL - Set B field value, then perturb; updates BDES

BCTRL.DRVH BMAX Maximum Desired Value, B field

BDELTAS.B TOLS(1) Warning Delta BDELTAS.C TOLS(2) Warning Fraction BDELTAS.E TOLS(3) Alarm Fraction BDELTAS.F TOLS(4) Monitor Fraction BDES BDES Desired B field Value

BMON BMON Physical Units val converted from IMON CALBOK - 1=Calibration successful

CALBTOD.TIME CTIM Last successful calibration time

CTRL - Control Request \u2013 magnet function

FBCKCTRL - 1=Magnet under feedback control

HSTA HSTA Control Bits

Translates SLC HSTA to individual EPICS

HSTACTRL -

records

IACT IACT Control Value from Hardware (Primary) IACT.ADEL ATOL(1) Standardization Delta

IACT.HIHI, LOLO IMMS Standardization, Calib Control Limits IACTPREVOK IPRV Last Good Readback ICTRL.DRVH,DRVL IMMO Control Limits

IDAC DACV DAC Readback

IDELTAS.C ATOL(2) Standardization Fraction

IDES IDES Desired Control Value (amperes)

IMON IMON Control Value from Hardware (Secondary) INSERVICE - 1=in service

IRIPL RIPL Ripple Current Readback

NOCTRL - 1=Can’t control this magnet; 0 otherwise

POLYCOEF.A to L IVBU Polynomial Coefficients

POLYCOEF.A to L IVBD Same as IVBU STAT STAT Status Bits

STATUS - Status of Control Action

STDZDIRECTION - UP/DOWN direction of standardization

STDZENABLE - 1=Standardize enabled

STDZIMAX or IDES.HIGH IMAX Max or min current during standardization STDZLOSTTOD.TIME ZTIM Last time standardization lost STDZTOD.TIME KTIM Last successful standardization time TRIMENABLE - 1=Trim enabled

TRIMTOD.TIME TTIM Last trim time

TRIMTRYCNT ITRY # of attempts required for trim

**Appendix C AIDA types**

Note: xxxA means array of type ‘xxx’

BOOLEAN BOOLEANA BYTE BYTEA CHAR CHARA DOUBLE DOUBLEA FLOAT FLOATA LONG LONGA

LONGDOUBLE LONGDOUBLEA LONGLONG LONGLONGA SHORT

SHORTA STRING STRINGA ULONG

ULONGA

ULONGLONG ULONGLONGA USHORT

USHORTA

WCHAR WCHARA WSTRING

WSTRINGA

**Appendix D Test PVs**

(Note: the name indicates the type of accepted data)

TEST:XX07:1:AI TEST:XX07:2:AI TEST:XX07:3:AI TEST:XX07:1:AO TEST:XX07:2:AO TEST:XX07:3:AO TEST:XX07:1:LONGIN TEST:XX07:2:LONGIN TEST:XX07:3:LONGIN TEST:XX07:1:LONGOUT TEST:XX07:2:LONGOUT TEST:XX07:3:LONGOUT TEST:XX07:1:STRINGIN TEST:XX07:2:STRINGIN TEST:XX07:3:STRINGIN TEST:XX07:1:STRINGOUT TEST:XX07:2:STRINGOUT TEST:XX07:3:STRINGOUT TEST:XX07:1:WFDOUBLE TEST:XX07:1:WFLONG TEST:XX07:1:WFSHORT TEST:XX07:2:WFDOUBLE TEST:XX07:2:WFLONG TEST:XX07:2:WFSHORT TEST:XX07:3:WFDOUBLE TEST:XX07:3:WFLONG TEST:XX07:3:WFSHORT